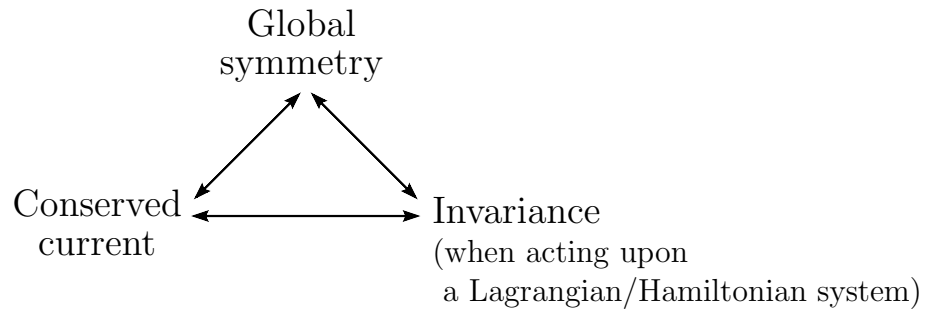


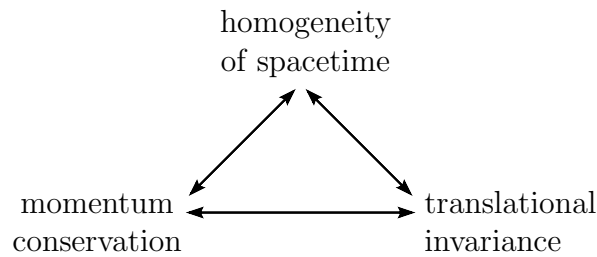
Introduction to the Standard Model

Lecture 2

Symmetries



As an example, consider



Classification

<u>global</u> :	spacetime symmetries	→	momentum, angular momentum, spin
	internal symmetries	→	weak isospin, charge, colour
<u>local</u> :	spacetime symmetries	→	gravity as a gauge theory
	internal symmetries	→	gauge theory

Basics of Group theory

(see tutorial for more details)

The Standard Model requires knowledge of the groups, $U(1)$, $SU(2)$, and $SU(3)$, along with some of their matrix representations and associated Lie-algebras.

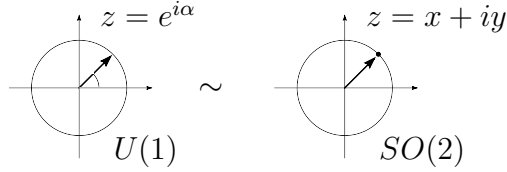
The $U(1)$ group

Each group element of $U(1)$ can be represented by a pure phase factor, $e^{i\alpha}$. The parameter, α , is real and continuous which indicates that $U(1)$ has an infinite set of group elements and is continuous.

Since $e^{i\alpha} = \cos \alpha + i \sin \alpha$, $U(1)$ is isomorphic to 2-by-2 rotation matrices, i.e. elements of $SO(2)$, which also form a Lie-group:

$$e^{i\alpha} = \cos \alpha + i \sin \alpha \quad \underset{\text{isomorphic}}{\sim} \quad \underbrace{\begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}}_{\exp\left(i\alpha \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}\right)} \in SO(2)$$

To see this consider the unit circle in the complex plane:



The $SU(N)$ group

i.) The $SU(N)$ group is defined as the collection of all unitary $N \times N$ matrices U , i.e. $U^{-1} = U^\dagger$, with determinant equal to one.

$$U \in SU(N) \Rightarrow \underbrace{UU^\dagger = \mathbb{1}}_{N^2 \text{ relations}}, \underbrace{\det(U) = 1}_{1 \text{ relation}}$$

As $U \in \mathbb{C}^{N \times N}$ has N^2 complex entries or $2N^2$ real entries, we are left with $2N^2 - N^2 - 1 = N^2 - 1$ independent parameters.

ii.) Consider the N -vector valued field, $\vec{\psi}$, transforming under $SU(N)$ as

$$\vec{\psi} \rightarrow \vec{\psi}' = U\vec{\psi} \quad \left(\psi'_j = U_{jl}\psi_l \quad \text{with } j, l = 1, \dots, N \right)$$

$\vec{\psi}$ is in the fundamental representation. We also note that $\vec{\psi}^\dagger \vec{\psi}$ is invariant under an $SU(N)$ transformation since

$$\begin{aligned} \vec{\psi}^\dagger \vec{\psi} &\rightarrow \vec{\psi}'^\dagger \vec{\psi}' = (U\vec{\psi})^\dagger U\vec{\psi} \\ &= \vec{\psi}^\dagger U^\dagger U \vec{\psi} \\ &= \vec{\psi}^\dagger \vec{\psi} \end{aligned}$$

iii.) A group element U can be expressed as an exponential

$$U(\Lambda_1, \dots, \Lambda_{N^2-1}) = \exp\left(i \sum_{a=1}^{N^2-1} \Lambda_a T_a\right) = \lim_{n \rightarrow \infty} \left(\mathbb{1} + i \frac{\Lambda_a}{n} T_a \right)^n$$

where Λ_a are real-valued and continuous, and $T_{a=1, \dots, N^2-1}$ are called the *generators* of the group. The conditions imposed by i.) and ii.) above restricts the T 's:

a.)

$$\begin{aligned}
U^\dagger U = \mathbb{1} &\Rightarrow \left(e^{i\varepsilon_a T_a} \right)^\dagger \left(e^{i\varepsilon_b T_b} \right) \\
&= \left(\mathbb{1} + i\varepsilon_a T_a + \mathcal{O}(|\varepsilon_a|^2) \right)^\dagger \left(\mathbb{1} + i\varepsilon_b T_b + \mathcal{O}(|\varepsilon_b|^2) \right) \\
&= \left(\mathbb{1} - i\varepsilon_a T_a^\dagger + \dots \right) \left(\mathbb{1} + i\varepsilon_b T_b + \dots \right) \\
&= \mathbb{1} + i\varepsilon_b \left(T_b - T_b^\dagger \right) + \dots
\end{aligned}$$

We see that the generators must be Hermitian: $T_b = T_b^\dagger$.

b.)

$$\begin{aligned}
\det U = 1 &\Rightarrow \det \left(e^{i\varepsilon_a T_a} \right) \\
&= 1 + i\varepsilon_a \text{tr} \left(T_a \right) + \dots
\end{aligned}$$

This implies that the generators must be traceless: $\text{tr} \left(T_a \right) = 0$.

Lie Algebra

The generators of $SU(N)$ obey an important property. Evaluate

$$U = U_2^{-1} U_1^{-1} U_2 U_1 \in SU(N) \quad (1)$$

by using

$$\begin{aligned}
U &= \mathbb{1} + i\lambda_c T_c + \dots \\
U_1 &= \mathbb{1} + i\varepsilon_a T_a - \frac{1}{2}(\varepsilon \cdot T)^2 + \dots \Leftrightarrow U_1^{-1} = U_1^\dagger = \mathbb{1} - i(\varepsilon \cdot T) - \frac{1}{2}(\varepsilon \cdot T)^2 + \dots \\
U_2 &= \mathbb{1} + i\delta_b T_b - \frac{1}{2}(\delta \cdot T)^2 + \dots \Leftrightarrow U_2^{-1} = U_2^\dagger = \mathbb{1} - i(\delta \cdot T) - \frac{1}{2}(\delta \cdot T)^2 + \dots
\end{aligned}$$

One gets

$$RHS \text{ of (1)} = \mathbb{1} - i(\delta \cdot T + \varepsilon \cdot T - \delta \cdot T - \varepsilon \cdot T) + \varepsilon_a \delta_b \left(T_a T_b - T_b T_a \right) + \dots$$

compared to the LHS of (1)

$$\mathbb{1} + i\lambda_c T_c + \dots = \mathbb{1} + \varepsilon_a \delta_b [T_a, T_b] + \dots$$

results into

$$[T_a, T_b] = if_{abc} T_c \quad f_{abc} \in \mathbb{R}$$

The f_{abc} 's are anti-symmetric *structure constants* of the Lie group. The *generators*, T_a , with such a property, form the so-called *Lie-algebra* associated to the Lie-group.

$$U = \underbrace{\exp \left(i\Lambda_a T_a \right)}_{\text{whole group}} = \underbrace{\mathbb{1} + i\Lambda_a T_a + \dots}_{\text{local elements define the properties of the whole group}}$$

Note The Lie group forms a compact manifold; the algebra is defined on the tangent to the unit element.

We choose a normalisation, $\text{tr}(T_a T_b) = T_R \delta_{ab}$ with $T_R = \frac{1}{2}$ (convention) such that

$$f_{abc} = -2i \text{tr}([T_a, T_b] T_c)$$

Important Examples

$SU(2)$

The generators are proportional to the Pauli matrices: $T_a = \frac{1}{2} \sigma^a$.

The algebra is given as: $[\frac{\sigma^a}{2}, \frac{\sigma^b}{2}] = i \varepsilon^{abc} \frac{\sigma^c}{2}$ where the structure constants are defined by the totally anti-symmetric epsilon tensor ε^{abc} . Remember that

$$\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$SU(3)$

The algebra is: $[\frac{\lambda^a}{2}, \frac{\lambda^b}{2}] = i f^{abc} \frac{\lambda^c}{2}$ where the λ^a 's are the Gell-Mann matrices,

$$\lambda^1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda^2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda^3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda^4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\lambda^5 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} \quad \lambda^6 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \lambda^7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad \lambda^8 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

The structure constants are:

$$f^{123} = 1$$

$$f^{147} = f^{246} = f^{345} = f^{316} = f^{257} = f^{637} = \frac{1}{2}$$

$$f^{458} = f^{678} = \frac{\sqrt{3}}{2}$$

$$f^{\text{other}} = 0$$

Note that we can see the $SU(2)$ subgroup in $SU(3)$:

$$\lambda^1 = \begin{pmatrix} \sigma^1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \lambda^2 = \begin{pmatrix} \sigma^2 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \lambda^3 = \begin{pmatrix} \sigma^3 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Exercise check all the above