# **Electromagnetism - Lecture 15**

# Waves in Conductors

- Absorption in Conductors
- Skin Depth
- Reflection at Conducting Surfaces
- Radiation Pressure
- Power Dissipation
- Conservation of Electromagnetic Energy

## **Maxwell's Equations in Conductors**

Maxwell's Equations M1-3 are as for insulators:

$$\nabla .\mathbf{D} = \rho_C \qquad \nabla .\mathbf{B} = 0$$
$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

but M4 in conductors includes a free current density  $\mathbf{J}_C = \sigma \mathbf{E}$ :

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J}_{\mathbf{C}}$$
$$\nabla \times \mathbf{B} = \mu_0 \epsilon_r \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} + \mu_0 \sigma \mathbf{E}$$

where we have again assumed that  $\mu_r = 1$ 

## Solution of M1-4 in Conductors

Taking the curl of M3:

$$\nabla \times (\nabla \times \mathbf{E}) = -\frac{\partial}{\partial t} (\nabla \times \mathbf{B}) = \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E}$$

using M1 with the assumption that the free charge density is zero:

$$\nabla \rho_c = \epsilon_r \epsilon_0 \nabla (\nabla \cdot \mathbf{E}) = 0$$

Subtituting for  $\mathbf{B}$  from M4 leads to a modified wave equation:

$$\nabla^2 \mathbf{E} = \frac{\partial}{\partial t} (\nabla \times \mathbf{B}) = \mu_0 \epsilon_r \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2} + \mu_0 \sigma \frac{\partial \mathbf{E}}{\partial t}$$

The first order time derivative is proportional to the conductivity  $\sigma$ This acts as a damping term for waves in conductors

Notes:		
Diagrams:		

#### **Plane Waves in Conductors**

The solution can be written as an attenuated plane wave:

$$E_x = E_0 e^{i(\omega t - \beta z)} e^{-\alpha z}$$

Substituting this back into the modified wave equation:

$$(-i\beta - \alpha)^2 E_0 = \mu_0 \epsilon_r \epsilon_0 (i\omega)^2 E_0 + \mu_0 \sigma(i\omega) E_0$$

Equating the real and imaginary parts:

$$-\beta^2 + \alpha^2 = -\mu_0 \epsilon_r \epsilon_0 \omega^2 \qquad \qquad 2\beta\alpha = \mu_0 \sigma\omega$$

For a good conductor with  $\sigma \gg \epsilon_r \epsilon_0 \omega$ :

$$\alpha = \beta = \sqrt{\frac{\mu_0 \sigma \omega}{2}}$$

For a perfect conductor  $\sigma \to \infty$  there are no waves and  $\mathbf{E} = 0$ 

## Skin Depth

The attenuation length in a conductor is known as the **skin depth**:

$$\delta = \frac{1}{\alpha} = \sqrt{\frac{2}{\mu_0 \sigma \omega}}$$

Skin depths for a good conductor (metal):

- $\delta \approx 10 cm$  at  $\nu = 50 Hz$  (mains frequency)
- $\delta \approx 10 \mu m$  at  $\nu = 50 MHz$  (radio waves)

High frequency waves are rapidly attenuated in good conductors

Practical application of this for RF shielding of sensitive equipment against external sources of EM waves.

## Magnetic Field of Plane Wave

The magnetic field of a plane wave in a good conductor can be found using M4:

$$\frac{\partial H_y}{\partial z} = -\sigma E_x = -\sigma E_0 e^{i(\omega t - \alpha z)} e^{-\alpha z}$$

where we neglect the term in the wave equation proportional to  $\epsilon_r$ 

$$H_y = \frac{\sigma E_0}{(1+i)\alpha} e^{i(\omega t - \alpha z)} e^{-\alpha z} = H_0 e^{i(\omega t - \alpha z - \pi/4)} e^{-\alpha z}$$

Note that there is a *phase shift* of  $\pi/4$  between **E** and **H** The amplitude ratio depends on the ratio of  $\sigma$  and  $\omega$ :

$$\frac{H_0}{E_0} = \sqrt{\frac{\sigma}{\mu_0 \omega}}$$

In a good conductor  $H_0 \gg E_0$  and they are no longer related by c!

Notes:		
Diagrams:		

#### **Reflection at a Conducting Surface**

We just consider the case of **normal incidence** The incident wave has:

$$\mathbf{E}_{I} = E_{0I}e^{i(\omega t - k_{1}z)}\mathbf{\hat{x}} \qquad \mathbf{B}_{I} = \frac{E_{0I}}{c}e^{i(\omega t - k_{1}z)}\mathbf{\hat{y}}$$

The reflected wave has:

$$\mathbf{E}_R = E_{0R} e^{i(\omega t + k_1 z)} \mathbf{\hat{x}} \qquad \mathbf{B}_R = \frac{E_{0R}}{c} e^{i(\omega t + k_1 z)} \mathbf{\hat{y}}$$

The transmitted wave inside the conductor has:

$$\mathbf{E}_T = E_{0T} e^{i(\omega t - \alpha z)} e^{-\alpha z} \mathbf{\hat{x}} \qquad \mathbf{B}_T = \frac{\alpha}{\omega} (1 - i) E_{0T} e^{i(\omega t - \alpha z)} \mathbf{\hat{y}}$$

For a perfect conductor  $\mathbf{E}_T = 0$  and the wave is completely reflected

#### Boundary Conditions at Conducting Surface

From **H** tangential:

$$\frac{1}{\mu_0} (B_{0I} - B_{0R}) = \frac{1}{\mu_0} B_{0T}$$
$$\sqrt{\epsilon_0} (E_{0I} - E_{0R}) = \sqrt{\frac{\sigma}{2\omega}} (1 - i) E_{0T}$$

From **E** tangential:

$$E_{0I} + E_{0R} = E_{0T}$$

The reflected amplitude is:

$$\frac{E_{0R}}{E_{0I}} = -\frac{(\sqrt{\sigma/2\omega\epsilon_0}(1-i)-1)}{(\sqrt{\sigma/2\omega\epsilon_0}(1-i)+1)}$$

The - sign gives a phase change  $\pi$  on reflection from a conductor

### **Radiation Pressure**

The reflection coefficient is:

$$\mathcal{R} = \frac{E_{0R}^2}{E_{0I}^2} \approx 1 - 2\sqrt{\frac{2\omega\epsilon_0}{\sigma}}$$

For a good conductor  $\sigma >> 2\omega\epsilon_0, \mathcal{R} \to 1$ .

A metallic surface is a good reflector of electromagnetic waves.

The reflection reverses the direction of the Poynting vector  $\mathbf{N} = \mathbf{E} \times \mathbf{H}$  which measures energy flux

There is a **radiation pressure** on a conducting surface:

$$\mathbf{P} = \frac{2 < \mathbf{N} >}{c} = \epsilon_0 E_0^2$$

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Diagrams:		

#### **Power Dissipation in Skin Depth**

The transmission coefficient is initially:

$$\mathcal{T} = \frac{E_{0T}^2}{E_{0I}^2} \approx 2\sqrt{\frac{2\omega\epsilon_0}{\sigma}}$$

but this rapidly attenuates away within the skin depth

Power is dissipated in the conduction currents

$$\frac{dP}{d\tau} = \mathbf{J}.\mathbf{E} = \sigma |E|^2$$

Time-averaging and integrating over the skin depth:

$$<\frac{dP}{dA}> = -\frac{\delta}{2}\sqrt{2\sigma\omega\epsilon_0}E_{0I}^2 = \epsilon_0 E_{0I}^2 c$$

This result balances the radiation pressure

## **Conservation of Electromagnetic Energy**

The power transferred to a charge moving with velocity  $\mathbf{v}$  is:

$$P = \mathbf{F} \cdot \mathbf{v} = q \mathbf{E} \cdot \mathbf{v}$$

In terms of current density  $\mathbf{J} = Ne\mathbf{v}$ :

$$P = \int_V \mathbf{J}.\mathbf{E}d au$$

We can use M4 to replace J:

$$\int_{V} \mathbf{J} \cdot \mathbf{E} d\tau = \int_{V} [\mathbf{E} \cdot (\nabla \times \mathbf{H}) - \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t}] d\tau$$

The first term can be rearranged using:

$$\nabla . (\mathbf{E} \times \mathbf{H}) = \mathbf{H} . (\nabla \times \mathbf{E}) - \mathbf{E} . (\nabla \times \mathbf{H})$$

Notes:		
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and M3 can be used to replace  $\nabla \times \mathbf{E}$ :

$$\int_{V} \mathbf{J} \cdot \mathbf{E} d\tau = -\int_{V} [\nabla \cdot (\mathbf{E} \times \mathbf{H}) + \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t}] d\tau$$

The integral over the volume  $d\tau$  can be removed to give local energy conservation:

$$\mathbf{J}.\mathbf{E} = -\left[\nabla.\mathbf{N} + \frac{\partial U_E}{\partial t} + \frac{\partial U_M}{\partial t}\right]$$

- Power dissipated in currents is **J.E**
- Change in energy flux is div of Poynting vector  $\nabla .(\mathbf{E} \times \mathbf{H})$
- Time variation of electric field energy density is  $\partial(\mathbf{D}.\mathbf{E})/\partial t$
- Time variation of magnetic field energy density is  $\partial(\mathbf{B}.\mathbf{H})/\partial t$